

ABSTRACT OF THE DISCLOSURE

A unit for the servo-assisted operation of a motor-vehicle gearbox comprises an actuator which can control the combined movement of a pair of mechanical operating members of the gearbox, for selection and engagement, respectively, in order to engage one of the transmission ratios of the gearbox in dependence on the position of a remote gearshift lever. The actuator is remote from the gearbox and is connected to the mechanical operating members by means of push-pull cables.

(Figure 1)

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